



ARTICLE INFO

Article History:

Received: 11 May 2020
Revised: 24 August 2020
Accepted: 8 September 2020
Available online: 2 October 2020

Keywords:

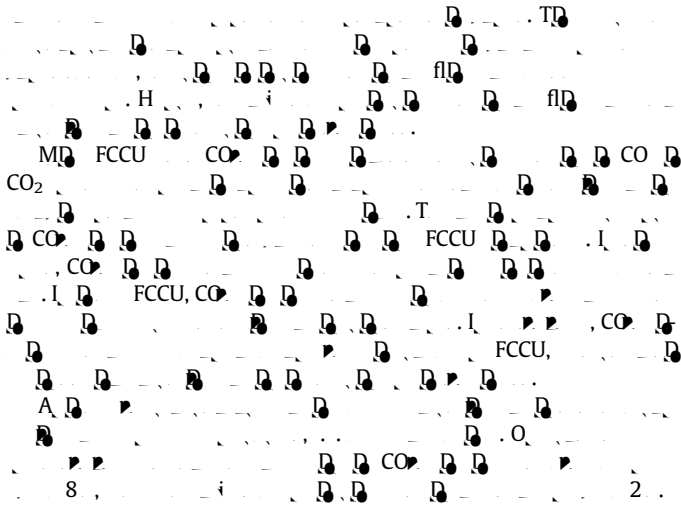
Control
Disturbance
Nonlinear
Observer
NCO
Fuzzy

ABSTRACT

This paper considers the disturbance rejection control problem for a class of nonlinear systems with unknown disturbance. The disturbance is assumed to be a piecewise constant signal. A nonlinear observer is designed to estimate the disturbance. The control law is designed based on the estimated disturbance. The stability of the closed-loop system is proved. Simulation results are provided to verify the effectiveness of the proposed control method.

1. Introduction

In this paper, we consider the disturbance rejection control (PSE) problem for a class of nonlinear systems. The disturbance is assumed to be a piecewise constant signal. The control law is designed based on the estimated disturbance. The stability of the closed-loop system is proved. Simulation results are provided to verify the effectiveness of the proposed control method.



3. Hybrid parametric dynamic optimization

3.1. Mathematical formulation of hybrid parametric dynamic optimization

The dynamic optimization problem is formulated as a differential-algebraic equation (DAE):

$$\dot{x}_d = f_d(t, x_d(t), x_a(t), u(t), \bar{u}) \tag{1}$$

$$0 = f_a(t, x_d(t), x_a(t), u(t), \bar{u}) \tag{1}$$

$$x_d(t) \in R^{n_d} / x_a(t) \in R^{n_a} ; u(t) / \bar{u} \tag{1}$$

$$J(u(t), \bar{u}) = \int_{t_0}^{t_f} (-r(t, x_d(t), x_a(t), u, \bar{u}) + c_1(t, x_d(t), x_a(t), u, \bar{u})) dt + c_2(\bar{u}) \tag{2}$$

$$\tilde{x} = -r + c_1 \tag{3}$$

$$\tilde{x}(t_0) = 0 \tag{4}$$

$$u(t), \bar{u} J(x(t_f), \bar{u}) = \tilde{x}(t_f) + c_2(\bar{u}) \tag{5}$$

$$x(t) = (x_d(t)^T, x_a(t)^T)^T \tag{5}$$

$$x^{lb} \leq x(t) \leq x^{ub} \tag{6}$$

$$u^{lb} \leq u(t) \leq u^{ub} \tag{6}$$

$$x^{lb} = ((x_d^{lb})^T, (x_a^{lb})^T)^T, x^{ub} = ((x_d^{ub})^T, (x_a^{ub})^T)^T, x_d^{lb}, x_d^{ub}, x_a^{lb}, x_a^{ub} \tag{7}$$

$$\bar{u}^{lb} \leq \bar{u} \leq \bar{u}^{ub} \tag{7}$$

$$x^{flb} \leq x(t_f) \leq x^{fub} \tag{8}$$

$$x^{flb} = ((x_d^{flb})^T, (x_a^{flb})^T)^T, x^{fub} = ((x_d^{fub})^T, (x_a^{fub})^T)^T, x_d^{flb}, x_d^{fub}, x_a^{flb}, x_a^{fub} \tag{8}$$

Problem (P1):

$$u(t), \bar{u} J(x(t_f), \bar{u}) \tag{9}$$

$$x_d(t_0) = x_d^0 \tag{9}$$

$$\dot{x}_d = f_d(t, x_d(t), x_a(t), u(t), \bar{u}) \tag{9}$$

$$0 = f_a(t, x_d(t), x_a(t), u(t), \bar{u}) \tag{9}$$

$$G_{\bar{u}}(\bar{u}) \leq 0 \tag{9}$$

$$G_u(u(t)) \leq 0 \tag{9}$$

$$G_p(x(t)) \leq 0 \tag{9}$$

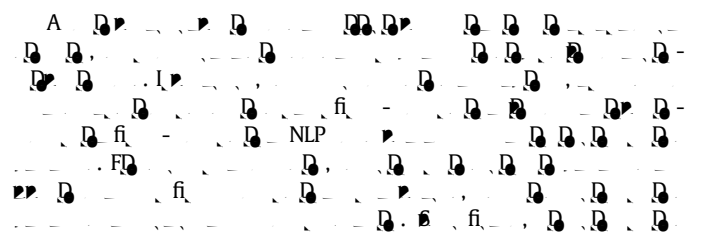
$$G_e(x(t_f)) \leq 0 \tag{9}$$

$$G_{\bar{u}}(\bar{u}) = \begin{pmatrix} \bar{u} - \bar{u}^{ub} \\ \bar{u}^{lb} - \bar{u} \end{pmatrix} \tag{9}$$

$$G_u(u(t)) = \begin{pmatrix} u(t) - u^{ub} \\ u^{lb} - u(t) \end{pmatrix} \tag{9}$$

$$G_p(x(t)) = \begin{pmatrix} x(t) - x^{ub} \\ x^{lb} - x(t) \end{pmatrix} \tag{9}$$

$$G_e(x(t_f)) = \begin{pmatrix} x(t_f) - x^{fub} \\ x^{flb} - x(t_f) \end{pmatrix} \tag{9}$$



$$u(t) \in D, \quad u(t) \approx \hat{u}^N(t) = \sum_{i=1}^N u_i^N \phi_i^N(t) \quad (10)$$

$$D^N = \{ \phi_1^N(t), \phi_2^N(t), \dots, \phi_N^N(t) \}, \quad u_i^N \in D, \quad \phi_i^N(t) \in U, \quad \phi_i^N(t) \cap \phi_j^N(t) = 0 \quad (i \neq j), \quad \forall i \neq j, \quad \langle \phi_i^N(t), \phi_j^N(t) \rangle = 0 \quad \forall i \neq j, \quad D_N, \quad \text{FD}, \quad N \geq 1, \quad t_0 < t_1 < t_2 < \dots < t_N = t_f, \quad \phi_i^N(t) = \begin{cases} 1, & t_{i-1} \leq t \leq t_i \\ 0, & \text{otherwise} \end{cases} \quad (11)$$

$$\hat{u}_N = ((u_1^N)^T, \dots, (u_N^N)^T)^T, \quad y^u(t) = y^l(t) - y^u(t), \quad y^l(t) = y^u(t) = 0, \quad y^l(t_0) = 0, \quad y^u(t_0) = 0, \quad y^l(t_f) = 0, \quad y^u(t_f) = 0, \quad \text{MIP}, \quad \hat{u}_N, \quad \text{NLP}, \quad \text{P2}.$$

Problem (P2):

$$\hat{u}_N, \bar{u}^j(x(t_f), \bar{u}) \quad (12)$$

$$MX(t_0) = X_0 \quad (12)$$

$$M\dot{X}(t) = F(t, X(t), \hat{u}_N, \bar{u}) \quad (12)$$

$$G(\bar{u}, \hat{u}_N, X(t_f)) \leq 0 \quad (12)$$

$$M = \begin{pmatrix} 1, \dots, 1, 0, \dots, 0 \\ 3n_d + 2n_a & n_a \end{pmatrix} \quad (12)$$

$$X(t) = \begin{pmatrix} x_d(t) \\ x^b(t) \\ x_a(t) \end{pmatrix} \quad (12)$$

$$X_0 = \begin{pmatrix} x_d^0 \\ 0 \\ 0 \end{pmatrix} \quad (12)$$

$$F(t, X(t), \hat{u}_N, \bar{u}) = \begin{pmatrix} f_d(t, x_d(t), x_a(t), \hat{u}_N, \bar{u}^j) \\ f_b(t, x(t)) \\ f_a(t, x_d(t), x_a(t), \hat{u}_N, \bar{u}^j) \end{pmatrix} \quad (12)$$

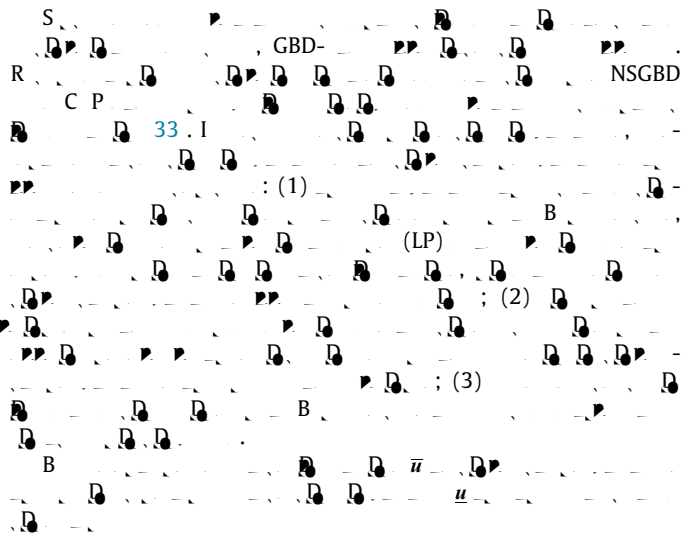
$$f_b(t, x(t)) = \begin{pmatrix} 0, x^{lb} - x(t) \\ 0, x(t) - x^{ub} \end{pmatrix} \quad (12)$$

$$G(\bar{u}, \hat{u}_N, X(t_f)) = \begin{pmatrix} G_{\bar{u}}(\bar{u}) \\ G_u(\hat{u}_N) \\ G_e(x^b(t_f)) \\ G_e(x(t_f)) \end{pmatrix} \quad (12)$$

$$G_u(\hat{u}_N) = \begin{pmatrix} G_u(u_1^N) \\ \vdots \\ G_u(u_N^N) \end{pmatrix} \quad (12)$$

$$G_e(x^b(t_f)) = x^b(t_f) \quad (12)$$

3.2. Nonconvex sensitivity-based generalized Benders decomposition



$$h(\bar{u}, u) = u - \bar{u} = 0 \quad (13)$$

Problem (P3):

$$\hat{u}_N, \bar{u}^j(x(t_f), \bar{u}_a) \quad (14)$$

$$MX(t_0) = X_0 \quad (14)$$

$$M\dot{X}(t) = F(t, X(t), \hat{u}_N, \bar{u}^j) \quad (14)$$

$$G(\bar{u}_a, \hat{u}_N, X(t_f)) \leq 0 \quad (14)$$

Problem (P4):

$$(\hat{u}_N, \bar{u}_b, \mu_a^j) = \hat{u}_N, \bar{u}^j(x(t_f), \bar{u}) \quad (15)$$

$$MX(t_0) = X_0 \quad (15)$$

$$M\dot{X}(t) = F(t, X(t), \hat{u}_N, \bar{u}) \quad (15)$$

$$G(\bar{u}, \hat{u}_N, X(t_f)) \leq 0 \quad (15)$$

$$h(\bar{u}, \bar{u}_a^j) = 0 \quad (15)$$

$$\mu_a^j \quad (15)$$

Problem (P5):

$$(\hat{u}_{N,c}^j, \hat{u}_c^j) = \arg \min_{\hat{u}_N, \hat{u}} \|\hat{u} - \hat{u}_t^j\|_A^2 \quad (16)$$

$$MX(t_0) = X_0 \quad (16)$$

$$M\dot{X}(t) = F(t, X(t), \hat{u}_N, \hat{u}) \quad (16)$$

$$G(\hat{u}, \hat{u}_N, X(t_f)) \leq 0 \quad (16)$$

$$\|\hat{u} - \hat{u}^j\|_A^2 = (\hat{u} - \hat{u}^j)^T A (\hat{u} - \hat{u}^j) \quad (16)$$

Problem (P6):

$$(\alpha_d^j, \hat{u}_{N,d}^j, \hat{u}_d^j | \mu_b^j) = \arg \min_{\alpha, \hat{u}_N, \hat{u}} \alpha \quad (17)$$

$$MX(t_0) = X_0 \quad (17)$$

$$M\dot{X}(t) = F(t, X(t), \hat{u}_N, \hat{u}) \quad (17)$$

$$G(\hat{u}, \hat{u}_N, X(t_f)) - \alpha \leq 0 \quad (17)$$

$$h(\hat{u}, \hat{u}_c^j) = 0 \quad (17)$$

$$\mu_c^j \cdot (\hat{u} - \hat{u}^{ub}) \leq 0, i \in K_u \quad (18)$$

$$\mu_c^i \cdot (\hat{u} - \hat{u}^{ub}) \leq 0, i \in K_u \quad (18)$$

$$\mu_d^i \cdot (\hat{u} - \hat{u}^{lb}) \leq 0, i \in K_l \quad (18)$$

$$\mu_c^i = (\underbrace{0, \dots, 0}_{i-1}, \underbrace{1, 0, \dots, 0}_{L-i}), \mu_d^i = (\underbrace{0, \dots, 0}_{i-1}, \underbrace{-1, 0, \dots, 0}_{L-i}) \quad (18)$$

Problem (P7):

$$(\eta_b^k, \underline{u}_b^k | \mathbf{v}_a^k, \mathbf{v}_b^k, \mathbf{v}_c^k, \mathbf{v}_d^k) = \arg \min_{\eta, \underline{u}} \eta \quad (19)$$

$$\eta \geq J_a^j + \mu_a^j \cdot (\underline{u} - \hat{u}_a^j), j \in K_{feas} \quad (19)$$

$$\mu_b^j \cdot (\underline{u} - \hat{u}_c^j) \leq 0, j' \in K_{infeas} \quad (19)$$

$$\mu_c^i \cdot (\underline{u} - \hat{u}^{ub}) \leq 0, i \in K_u \quad (19)$$

$$\mu_d^i \cdot (\underline{u} - \hat{u}^{lb}) \leq 0, i \in K_l \quad (19)$$

$$K_u = \{i \in \{1, \dots, L\} : \mathbf{v}_c^k \neq 0\}, K_l = \{i \in \{1, \dots, L\} : \mathbf{v}_d^k \neq 0\}, K_{feas}, K_{infeas} \quad (19)$$

$$\Xi_a = \{j \in \{1, \dots, J\} : (\mathbf{v}_a^k)_j \neq 0\} \quad (20)$$

$$\Xi_b = \{j' \in \{1, \dots, J'\} : (\mathbf{v}_b^k)_{j'} \neq 0\} \quad (20)$$

$$\Xi_c = \{i \in \{1, \dots, L\} : (\mathbf{v}_c^k)_i \neq 0\} \quad (20)$$

$$\Xi_d = \{i' \in \{1, \dots, L'\} : (\mathbf{v}_d^k)_{i'} \neq 0\} \quad (20)$$

Problem (P8):

$$(\underline{u}_c^k) = \arg \min_{\underline{u}} \mu_a^k \cdot \underline{u} \quad (21)$$

$$\mu_b^j \cdot (\underline{u} - \hat{u}_c^j) \leq 0, j' \in K_{infeas} \quad (21)$$

$$\mu_c^i \cdot (\underline{u} - \hat{u}_i) \leq 0, i \in K_u \quad (21)$$

$$\mu_d^i \cdot (\underline{u} - \hat{u}_i) \leq 0, i' \in K_l \quad (21)$$

$$LBD > UBD \quad (22)$$

$$UBD - LBD < \varepsilon_1 \quad (22)$$

$$\|\mu_a^k / J_a^k\|_B \leq \varepsilon_2 \quad (23)$$

$$\|\underline{u}_b^k - \underline{u}_c^k\|_B \leq \varepsilon_3 \quad (23)$$

Algorithm 1: NSGBD with CVP for Problem (P1)

Step 1. D $t_0, t_f, \dots, t_0 < t_1 < t_2 < \dots < t_N = t_f$, $\hat{u}_N, F, \hat{u}_t^j, E, \dots$

$j = 1, j' = 1, K_{feas} = \emptyset, K_{infeas} = \emptyset, LBD = -\infty$; $\gamma, \varepsilon_1, \varepsilon_2, \varepsilon_3$.

Step 2. S $(P3) \hat{u}_a^j = \hat{u}_t^j, O, \dots$

(1) P $(P3) \hat{u}_{N,a}^j, J_a^j, \dots$

(2) UBD - LBD $< \varepsilon_1, O, \dots$

(a) $|\Xi_b| + |\Xi_c| + |\Xi_d| = 0 (\hat{u}_a^j = \hat{u}_t^j)$, I E, (23)

(b) $|\Xi_b| + |\Xi_c| + |\Xi_d| \neq 0 (\hat{u}_a^j \neq \hat{u}_t^j)$, S $(P4) \hat{u}_a^j = \hat{u}_t^j, \mu_a^j, UBD = J_a^j, O, \dots$

(P8) $\hat{u}_a^j = \underline{u}_c^j, I E, (23)$ $\hat{u}_a^j = \hat{u}_t^j$, $(\hat{u}_{N,a}^j, \hat{u}_a^j)$.

$K_{feas} = \{K_{feas}, j\}; j = j + 1$.

(2) P $(P3) \hat{u}_{N,c}^j, \hat{u}_c^j, \dots$ $(P6) \hat{u}_c^j = (\hat{u}_{N,c}^j, \hat{u}_c^j), \alpha = 0$

$\mu_b^j \cdot K_{infeas} = K_{infeas}, j' = j' + 1$, R $(P7) \eta_b^j, \underline{u}_b^j, \mathbf{v}_a^j, \mathbf{v}_b^j, \mathbf{v}_c^j, \mathbf{v}_d^j$; $LBD = \eta_b^j, \hat{u}_t^j = \underline{u}_b^j$, R $(P5) \hat{u}_t^j = \hat{u}_c^j, \alpha = 0$.

Remark 1. T $(P3) \hat{u}_t^j = \hat{u}_c^j, (P4) \hat{u}_a^j = \hat{u}_t^j, \dots$

$\Xi_a = \{j \in \{1, \dots, J\} : (\mathbf{v}_a^k)_j \neq 0\}$, $\Xi_b = \{j' \in \{1, \dots, J'\} : (\mathbf{v}_b^k)_{j'} \neq 0\}$, $\Xi_c = \{i \in \{1, \dots, L\} : (\mathbf{v}_c^k)_i \neq 0\}$, $\Xi_d = \{i' \in \{1, \dots, L'\} : (\mathbf{v}_d^k)_{i'} \neq 0\}$.

$K_u = \{i \in \{1, \dots, L\} : \mathbf{v}_c^k \neq 0\}, K_l = \{i' \in \{1, \dots, L'\} : \mathbf{v}_d^k \neq 0\}, K_{feas}, K_{infeas}$.

$\hat{u}_a^j = \hat{u}_t^j, \mu_a^j, UBD = J_a^j, O, \dots$

(P5) $\hat{u}_a^j = \hat{u}_t^j, \mu_a^j, UBD = J_a^j, O, \dots$

$\alpha = 0$, P $(P7) \eta_b^j, \underline{u}_b^j, \mathbf{v}_a^j, \mathbf{v}_b^j, \mathbf{v}_c^j, \mathbf{v}_d^j$; $LBD = \eta_b^j, \hat{u}_t^j = \underline{u}_b^j$.

$\hat{u}_a^j = \hat{u}_t^j, \mu_a^j, UBD = J_a^j, O, \dots$

K_{infeas}, K_u, K_l , E. (22.)
 LBD, E. (23.) (23)
 P (P8)
 E. (23), T NSGBD
 S 2 A 1.

Remark 2. T NSGBD
 μ_a^j ()
 13 $\bar{\mu}$; 2
 38 NSGBD,

3.3. Novel implementation framework of optimal solution

A C P,
 MD, TD
 T

4. Hybrid parametric dynamic optimization of FCCU

4.1. Mathematical formulation of FCCU

The objective function for the hybrid optimization of FCCU is defined as follows:

$$J(T_{ra\ sp}(t), \{V_i\}_{i=1}^4, M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), \{V_i\}_{i=1}^4, M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), \{V_i\}_{i=1}^4, M_{pro})) dt + \sum_{i=1}^4 \int_{120(i-1)}^{120i} f(V_i) dt + \omega_3 M_{pro}$$

where $\omega_{1d}, \omega_{1n}, \omega_3$ are the weighting factors for the different objectives. The parameters are defined as follows:

- F_d : Feed flow rate
- F_n : Net flow rate
- f : Feed cost function
- $\{V_i\}_{i=1}^4$: Control variables
- M_{pro} : Production rate

$$J(T_{ra\ sp}(t), \{V_i\}_{i=1}^4, M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), \{V_i\}_{i=1}^4, M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), \{V_i\}_{i=1}^4, M_{pro})) dt + \sum_{i=1}^4 \int_{120(i-1)}^{120i} f(V_i) dt + \omega_3 M_{pro} \quad (25)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

4.2. Case 1: Combustion air as a continuous operation whereas CO promoter as a batch operation

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

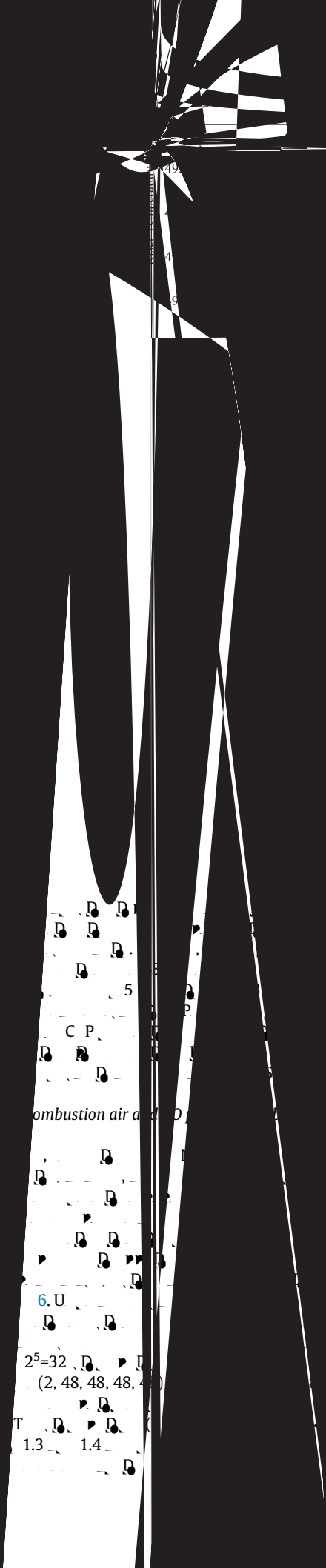
$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$

The constraints for the hybrid optimization of FCCU are defined as follows:

$$J(T_{ra\ sp}(t), V(t), M_{pro}) = \int_0^{480} (-\omega_{1d} F_d(t, T_{ra\ sp}(t), V(t), M_{pro}) - \omega_{1n} F_n(t, T_{ra\ sp}(t), V(t), M_{pro}) + f(V(t))) dt + \omega_3 M_{pro} \quad (26)$$



49

4

9

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

$\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$

C P

ombustion air and D

6. U

$2^5=32$
(2, 48, 48, 48, 48)

T

1.3 1.4

Table 4

	4.4	5	6	7	8	9	10
$M_{pro}(\cdot)$	2.5865	2.4590	2.7855	2.8738	2.8890	3.2639	3.3223
μ_M	8.9744	-21.541	27.047	25.754	20.927	53.115	58.887
$V_1(\cdot)$	49.034	49.061	49.064	49.064	49.065	49.068	49.068
μ_{V1}	-3480.3	-3515.4	-3471.9	-3479.8	-3490.8	-3480.0	-3468.3
$V_2(\cdot)$	48.952	48.977	48.978	48.979	48.979	48.980	48.981
μ_{V2}	-3456.5	-3485.2	-3471.7	-3476.6	-3461.9	-3448.0	-3434.7
V_{10}	1	2.3841	0	2.8	9		

$$M_{pro}^* \in (M_{pro}^k, M_{pro}^{10}) = (2.5865, 3.3223) \quad (28)$$

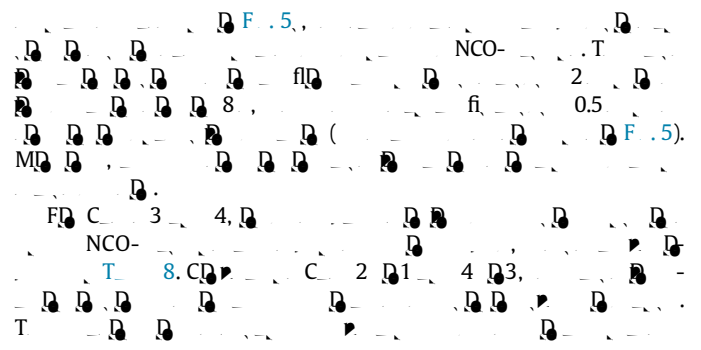
$$V_1^* \in (V_1^{10}, V_1^k) = (49.068, 49.072) \quad (28)$$

$$V_2^* \in (V_2^{10}, V_2^k) = (48.981, 48.983) \quad (28)$$

$$V_3^* \in (V_3^{10}, V_3^k) = (48.931, 48.932) \quad (28)$$

$$V_4^* \in (V_4^{10}, V_4^k) = (48.896, 48.897) \quad (28)$$

$(M_{pro}^{10}, V_1^{10}, V_2^{10}, V_3^{10}, V_4^{10})$,
 $M_{pro} \in (3.3223, 3.3223)$, $V_1 \in (49.076, 49.080)$, $V_2 \in (48.988, 48.992)$, $V_3 \in (48.938, 48.942)$, $V_4 \in (48.904, 48.908)$.
 $M_{pro} = 3.3223$, $V_1 = 49.078$, $V_2 = 48.990$, $V_3 = 48.940$, $V_4 = 48.906$.
 $J = 1890.4$



15 F. L. S., G. A. FCCU I. A. fi. FCC. A. P. S. (P. S.) 1994;10(2):21–8.

16 F. L. S., G. A. FCCU II. MD. A. P. S. (P. S.) 1994;10(3):25–35.

17 L. F. H. C. S., H. J. A. FCC. fi. 1993;24(9):1–8.

18 H. M., L. S. R. D. fi. 2017 36 C. (CCC). IEEE; 2017. 2990–5.

19 G. H., L. S., F. S. D. E. D. fi. J. T. C. E. 2019;96:104–13.

20 A. S. M., K. A. T. P. D. fi. SIAM J. C. 2004;43(3):1094–119.

21 H. R. A. D. M. S. 1966;12(5):317–48.

22 L. J. L. H. 2020;37:100902. DOI: 10.1016/j. 2020.100902.

23 H. A. M. D. C. E. 2010;34(11):1873–89.

24 S. M. S. D. K. B., T. M. D. C. E. 2005;29(8):1731–51.

25 B. L. T., C. A. M., A. A. C. E. S. 2002;57(4):575–93.

26 B. L. T., A. D. C. E. P. I. 2007;46(11):1043–53.

27 K. C., L. B. D., H. G., S. J. P. E. fi. J. P. D. C. D. 2012;22(3):540–50.

28 L. D. B., B. I. B. D., H. G., S. J. P. A. fi. SQP. C. E. 2003;27(2):157–66.

29 B. T., C. A., C. M., D. C. E. 2000;24(2–7):1201–7.

30 H. D. L. P. D. I. E. C. R. 2018;57(18):6292–302.

31 S. B., P. S., B. D., D. D. C. E. 2003;27(1):1–26.

32 S. B., B. D., D., E. P., S. D. C. E. 2003;27(1):27–44.

33 L. J., F. L. D. B. C. E. (U. R.)

34 R. L. D., F. M. FCCU. CO. D. CIESC J 2013;64(8):2930–7.

35 R. L. D., F. E. C. J. C. E. 2014;22(5):531–7.

36 R. L. D., F. E. D. fi. I. E. C. R. 2014;53(1):287–304.

37 C. M., S. E. P. P. I. M., E. A.-J. P. D. 2000;214(2):153–64.

38 L. P. B. C. E. 2013;55:97–108.

39 S. B., B. D., R. I. E. C. R. 2007;46(2) 492–50.

40 G. S. S., B., B. D., N. D. I. P. 2004 A. IEEE; 2004. 34–9.

41 L. C. D., L. I. E. C. R. 2013;52(2):798–808.

42 F. G., S., B., B. D., D. U. J. P. D. 2005;15(6):701–12.

43 G. S. S., B., B. D., D. C. E. 2009;33(1):191–8.

44 L. S., F. M., H. A. NCO. J. P. D. C. D. 2020;89:30–44.